# Hyperbolic systems of equations and double null foliations of spacetime

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October 2024

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• Brief general relativity overview

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- Double null foliations

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- Bianchi equations and general hyperbolic systems

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- Algebraic constraints for linearized Bianchi equations

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### Definition

A **spacetime** is a 4-dimensional Lorentzian manifold (M, g).

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Hyperbolic systems & DNFs

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A **spacetime** is a 4-dimensional Lorentzian manifold (M,g). Tangent vectors v are classified as timelike, null, or spacelike according to whether g(v,v) is negative, zero, or positive (respectively). Hypersurfaces  $\Sigma \subset M$  are *spacelike* if  $\nu_{\Sigma}$  is timelike, and *null* if  $\nu_{\Sigma}$  is null.



### Remark

Massless radiation (electromagnetic, gravitational,...) travels along null hypersurfaces

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#### Einstein equations

A Lorentzian manifold (M, g) satisfies the **Einstein equations** if

$$\operatorname{Ric}(g)_{\mu\nu} - \frac{1}{2}\operatorname{Scal}(g)g_{\mu\nu} = T_{\mu\nu}, \tag{E}$$

where  $T_{\mu\nu}$  represents the matter distribution in spacetime. In particular, (M,g) satisfies the **vacuum Einstein equations** if

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#### **Bianchi** equations

In a vacuum spacetime, the Bianchi equations for the curvature are

$$\nabla_{[\alpha} W_{\beta\gamma]\delta\rho} := \nabla_{\alpha} W_{\beta\gamma\delta\rho} + \nabla_{\beta} W_{\gamma\alpha\delta\rho} + \nabla_{\gamma} W_{\alpha\beta\delta\rho} = 0.$$
 (B)

A double null foliation is a choice of two "optical" functions

 $u, \underline{u}: M \to \mathbb{R}$ 

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Figure: A double null foliation of a spacetime (M, g)

We let γ = γ<sub>u,<u>u</u></sub> = g|<sub>S<sub>u,<u>u</u></sub></sub> be the (Riemannian) restriction of the spacetime metric to the spheres S<sub>u,<u>u</u></sub>

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- Write ∇ for the Levi-Civita connection of (M, g) and ♥ for the Levi-Civita connection of (S, γ)

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 Incredibly powerful tool in mathematical GR (stability, singularity formation, more) [Christodoulou, Klainerman-Nicolò, Klainerman-Rodnianski-Luk, Shlapentokh-Rothman, Taylor, Dafermos-Holzegel-Rodnianski-Taylor, Oh-Luk-Shlapentokh-Rothman, many others]



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- Well-suited for analysis of radiation (gravitational, electromagnetic,...) which *travels along null hypersurfaces*
- Characteristic IVP: prescribe initial data along  $C_0 \cup \underline{C}_0$

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Let  $e_3 = -\nabla \underline{u}, e_4 = -\nabla u$ . These are null vector fields with  $e_3$  tangent to  $\underline{C}_{\underline{u}}$  and  $e_4$  tangent to  $C_u$ .



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$$\rho[W] = \frac{1}{4}W(e_3, e_4, e_3, e_4) \qquad \sigma[W] = \frac{1}{4}*W(e_3, e_4, e_3, e_4)$$



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For any S-tangent tensorfield  $\xi$ , we write  $\bigvee_{3}\xi$ ,  $\bigvee_{4}\xi$  denote the projections of  $\nabla_{3}\xi$ ,  $\nabla_{4}\xi$  (respectively) to  $S_{u,\underline{u}}$ .

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# Null Bianchi equations

Decomposing the Bianchi equations for the Weyl tensor,

$$\nabla_{[\alpha} W_{\beta\gamma]\delta\rho} = 0,$$

in the null frame  $(e_{\mu})_{\mu=1}^{4}$ , gives the **null Bianchi equations.** 

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- $\Gamma$  are the Ricci coefficients (connection coefficients) of the foliation

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•  $\Gamma$  are the Ricci coefficients (connection coefficients) of the foliation These can be regarded as *propagation equations* for the Weyl tensor components  $\Psi[W]$  and are used to obtain  $L^p(S_{u,\underline{u}})$  and  $L^p(C_u)$ ,  $L^p(\underline{C}_{\underline{u}})$  estimates on  $\Psi$ .

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Goal: Study Einstein equations in a double null foliation

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• Expressing (VE) in a double null foliation gives the null Bianchi equations (for the curvature) & null structure equations (for the Ricci coefficients)

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Goal: Study Einstein equations in a double null foliation

- Expressing (VE) in a double null foliation gives the null Bianchi equations (for the curvature) & null structure equations (for the Ricci coefficients)
- These equations have excellent structure (propagation equations, hyperbolicity, elliptic equations on S<sub>u,<u>u</u></sub>)
- Even in works which don't explicitly use a double null foliation, null Bianchi & null structure used widely [Christodoulou-Klainerman, Zipser, Bieri,...]

Up to lower-order terms, the null Bianchi equations are:

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Notation:  $\nabla$  is the induced connection on the spheres  $S_{u,\underline{u}}$ , d/v is the divergence operator of  $S_{u,\underline{u}}$ ,  $\nabla \hat{\otimes}$  is the traceless part of the symmetrized covariant derivative, \* denotes the Hodge dual on the  $S_{u,u}$ . See [Christodoulou (2008)].

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**Key point: Bianchi pairs.** The principal part of equations on the *right* is (minus) the  $L^2(S_{u,\underline{u}})$ -adjoint of the principal part of the equations on the *left*,

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- Idea: extract structure of (B) and study its behavior. For 2N unknowns  $\{\Psi^{(i)}, \underline{\Psi}^{(i)}\}_{i=1}^{N}$ , consider the following system (**DNH**):

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Double null hyperbolic system (DNH)

$$\nabla_{3}\Psi^{(i)} = \mathcal{D}_{\Psi^{(i)}}\underline{\Psi}^{(1)} + E^{(i)}, \quad \nabla_{4}\underline{\Psi}^{(i)} = \mathcal{D}_{\underline{\Psi}^{(i)}}\Psi^{(i)} + \underline{E}^{(i)} \qquad (i = 1, \dots, N)$$

Notation:  $E^{(i)}, \underline{E}^{(i)}$  are "lower-order" terms;  $\mathcal{D}_{\Psi^{(i)}}, \mathcal{D}_{\underline{\Psi}^{(i)}}$  are first-order differential operators on  $S_{u,\underline{u}}$  (e.g.  $d/v, \nabla,$  etc.) which are "Bianchi-paired", i.e. they are  $L^2(S_{u,\underline{u}})$ -anti-adjoints of each other:

$$\int_{\mathcal{S}_{u,\underline{u}}} \phi \cdot \mathcal{D}_{\Psi^{(i)}} \psi \, d\mu_{\mathcal{S}_{u,\underline{u}}} = - \int_{\mathcal{S}_{u,\underline{u}}} \mathcal{D}_{\underline{\Psi}^{(i)}} \phi \cdot \psi \, d\mu_{\mathcal{S}_{u,\underline{u}}} \quad \forall \phi, \psi \in C^{\infty}(\mathcal{S}_{u,\underline{u}}).$$

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**Characteristic IVP:** Prescribe initial data  $\Psi_0^{(i)}$  along  $C_0$  and  $\underline{\Psi}_0^{(i)}$  along  $\underline{C}_0$ 

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The Bianchi pairing is essential to obtaining energy estimates for the system. Define the energy  $\ensuremath{\mathcal{E}}$ :

$$\mathcal{E}[\Psi](u,\underline{u})\coloneqq rac{1}{2}\int_{\mathcal{S}_{u,\underline{u}}}|\Psi|^2\,d\mu_{\mathcal{S}_{u,\underline{u}}}.$$

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Heuristic computation:

$$\nabla_{3}\mathcal{E}[\Psi](u,\underline{u}) = \int_{\mathcal{S}_{u,\underline{u}}} \Psi \cdot \nabla_{3} \Psi \, d\mu_{\mathcal{S}_{u,\underline{u}}}$$

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Heuristic computation:

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Heuristic computation:

$$\begin{split} \nabla_{3}\mathcal{E}[\Psi](u,\underline{u}) &= \int_{\mathcal{S}_{u,\underline{u}}} \Psi \cdot \nabla_{3} \Psi \, d\mu_{\mathcal{S}_{u,\underline{u}}} \\ &= \int_{\mathcal{S}_{u,\underline{u}}} \Psi \cdot \mathcal{D}_{\Psi} \underline{\Psi} \, d\mu_{\mathcal{S}_{u,\underline{u}}} \\ &= -\int_{\mathcal{S}_{u,\underline{u}}} \mathcal{D}_{\Psi} \Psi \cdot \underline{\Psi} \, d\mu_{\mathcal{S}_{u,\underline{u}}} + \text{lower order} \end{split}$$

The Bianchi pairing is essential to obtaining energy estimates for the system. Define the energy  $\ensuremath{\mathcal{E}}$ :

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Heuristic computation:

$$\begin{aligned} \nabla_{3}\mathcal{E}[\Psi](u,\underline{u}) &= \int_{S_{u,\underline{u}}} \Psi \cdot \nabla_{3}\Psi \, d\mu_{S_{u,\underline{u}}} \\ &= \int_{S_{u,\underline{u}}} \Psi \cdot \mathcal{P}_{\Psi} \underline{\Psi} \, d\mu_{S_{u,\underline{u}}} \\ &= -\int_{S_{u,\underline{u}}} \mathcal{P}_{\underline{\Psi}} \Psi \cdot \underline{\Psi} \, d\mu_{S_{u,\underline{u}}} + \text{lower order} \\ &= -\int_{S_{u,\underline{u}}} \nabla_{4} \underline{\Psi} \cdot \Psi \, d\mu_{S_{u,\underline{u}}} + \text{lower order} \\ &= -\nabla_{4}\mathcal{E}[\underline{\Psi}](u,\underline{u}) + \text{lower order}. \end{aligned}$$

Integrating

$$\nabla_{3}\mathcal{E}[\Psi](u,\underline{u}) + \nabla_{4}\mathcal{E}[\Psi](u,\underline{u}) =$$
lower order

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Integrating

$$abla_3 \mathcal{E}[\Psi](u,\underline{u}) + 
abla_4 \mathcal{E}[\Psi](u,\underline{u}) = \text{lower order}$$

gives

Energy estimates for DNH

$$\int_{\mathcal{C}_u} |\Psi|^2 \, d\mu_{\mathcal{C}_u} + \int_{\underline{\mathcal{C}}_{\underline{u}}} |\underline{\Psi}|^2 \, d\mu_{\underline{\mathcal{C}}_{\underline{u}}} \lesssim \text{Initial Data.}$$

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$$\begin{split} & \nabla_{3} \alpha[W] \approx \nabla \hat{\otimes} \beta[W] \\ & \nabla_{3} \beta[W] \approx \nabla \rho[W] + {}^{*} \nabla \sigma[W] \\ & \nabla_{3} (\rho[W], \sigma[W]) \approx (-\mathsf{d} i_{\mathsf{V}} \underline{\beta}[W], -\mathsf{c} i_{\mathsf{V}} \mathsf{r} \underline{\beta}[W]) \\ & \nabla_{3} \beta[W] \approx -\mathsf{d} i_{\mathsf{V}} \underline{\alpha}[W] \end{split}$$

$$\begin{split} & \nabla_{4}\beta[W] \approx \mathsf{d}\!\!/\mathsf{v}\alpha[W] \\ & \nabla_{4}(\rho[W], \sigma[W]) \approx (\mathsf{d}\!\!/\mathsf{v}\beta[W], -\mathsf{c}\!\!/\mathsf{r}\!\!/\mathsf{r}\beta[W]) \\ & \nabla_{4}\underline{\beta}[W] \approx -\nabla\!\!/\rho[W] + {}^{*}\nabla\!\!/\sigma[W] \\ & \nabla_{4}\underline{\alpha}[W] \approx -\nabla\!\!/\widehat{\otimes}\underline{\beta}[W] \end{split}$$

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• The Bianchi equations almost form a DNH.

$$\begin{split} \nabla_{3} \alpha[W] &\approx \nabla \hat{\otimes} \beta[W] \\ \nabla_{3} \beta[W] &\approx \nabla \rho[W] + {}^{*} \nabla \sigma[W] \\ \nabla_{3} (\rho[W], \sigma[W]) &\approx (-\mathsf{d} i \mathsf{v} \underline{\beta}[W], -\mathsf{c} \mathcal{q} \mathsf{r} \mathsf{l} \underline{\beta}[W]) \\ \nabla_{3} \beta[W] &\approx -\mathsf{d} i \mathsf{v} \underline{\alpha}[W] \end{split}$$

$$\begin{split} & \nabla_{4}\beta[W] \approx \mathsf{div}\alpha[W] \\ & \nabla_{4}(\rho[W], \sigma[W]) \approx (\mathsf{div}\beta[W], -\mathsf{crifrl}\beta[W]) \\ & \nabla_{4}\underline{\beta}[W] \approx -\nabla\rho[W] + {}^{*}\nabla\sigma[W] \\ & \nabla_{4}\underline{\alpha}[W] \approx -\nabla\hat{\otimes}\underline{\beta}[W] \end{split}$$

 The Bianchi equations almost form a DNH. Problem: They are overdetermined as an IVP!

$$\begin{split} \nabla_{3}\alpha[W] &\approx \nabla \hat{\otimes} \beta[W] \\ \nabla_{3}\beta[W] &\approx \nabla \rho[W] + {}^{*}\nabla \sigma[W] \\ \nabla_{3}(\rho[W], \sigma[W]) &\approx (-\mathsf{div}\underline{\beta}[W], -\mathsf{cu}\mathsf{rl}\underline{\beta}[W]) \\ \nabla_{3}\beta[W] &\approx -\mathsf{div}\underline{\alpha}[W] \end{split}$$

$$\begin{split} \nabla_{4}\beta[W] &\approx \mathsf{d}\!\!/\mathsf{v}\alpha[W] \\ \nabla_{4}(\rho[W], \sigma[W]) &\approx (\mathsf{d}\!\!/\mathsf{v}\beta[W], -\mathsf{c}\!\!/\mathsf{u}\!\mathsf{r}\!\!/\beta[W]) \\ \nabla_{4}\underline{\beta}[W] &\approx -\nabla\!\!/\rho[W] + {}^{*}\nabla\!\!/\sigma[W] \\ \nabla_{4}\underline{\alpha}[W] &\approx -\nabla\!\!/\widehat{\otimes}\beta[W] \end{split}$$

- The Bianchi equations *almost* form a DNH. **Problem:** They are overdetermined as an IVP!
- Other than α[W], α[W], each Weyl tensor component satisfies two independent equations

$$\begin{split} \nabla_{3}\alpha[W] &\approx \nabla \hat{\otimes} \beta[W] \\ \nabla_{3}\beta[W] &\approx \nabla \rho[W] + {}^{*}\nabla \sigma[W] \\ \nabla_{3}(\rho[W], \sigma[W]) &\approx (-\mathsf{div}\underline{\beta}[W], -\mathsf{cu}\mathsf{rl}\underline{\beta}[W]) \\ \nabla_{3}\beta[W] &\approx -\mathsf{div}\underline{\alpha}[W] \end{split}$$

$$\begin{split} & \nabla_{4}\beta[W] \approx \mathsf{div}\alpha[W] \\ & \nabla_{4}(\rho[W], \sigma[W]) \approx (\mathsf{div}\beta[W], -\mathsf{crifrl}\beta[W]) \\ & \nabla_{4}\underline{\beta}[W] \approx -\nabla\rho[W] + {}^{*}\nabla\sigma[W] \\ & \nabla_{4}\underline{\alpha}[W] \approx -\nabla\hat{\otimes}\underline{\beta}[W] \end{split}$$

- The Bianchi equations *almost* form a DNH. **Problem:** They are overdetermined as an IVP!
- Other than α[W], α[W], each Weyl tensor component satisfies two independent equations
- Fix: choose a subset of the equation to be *constraints* and the others to be *evolution* equations

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### Double null hyperbolic systems

$$\begin{split} \nabla_{3}\alpha[W] &\approx \nabla \hat{\otimes} \beta[W] \\ \nabla_{3}\beta[W] &\approx \nabla \rho[W] + {}^{*}\nabla \sigma[W] \\ \nabla_{3}(\rho[W], \sigma[W]) &\approx (-\mathsf{div}\underline{\beta}[W], -\mathsf{cu}\mathsf{rl}\underline{\beta}[W]) \\ \nabla_{3}\beta[W] &\approx -\mathsf{div}\underline{\alpha}[W] \end{split}$$

$$\begin{split} & \nabla_{4}\beta[W] \approx \mathsf{div}\alpha[W] \\ & \nabla_{4}(\rho[W], \sigma[W]) \approx (\mathsf{div}\beta[W], -\mathsf{crifrl}\beta[W]) \\ & \nabla_{4}\underline{\beta}[W] \approx -\nabla\rho[W] + {}^{*}\nabla\sigma[W] \\ & \nabla_{4}\underline{\alpha}[W] \approx -\nabla\hat{\otimes}\underline{\beta}[W] \end{split}$$

- The Bianchi equations *almost* form a DNH. **Problem:** They are overdetermined as an IVP!
- Other than α[W], α[W], each Weyl tensor component satisfies two independent equations
- Fix: choose a subset of the equation to be *constraints* and the others to be *evolution* equations
- Then hope that under the flow of the remaining equations, these constraints propagate if satisfied by the initial data (more on this later)

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Fix a background vacuum spacetime (M, g). In (B) replace Weyl tensor components  $\alpha[W], \beta[W]$ , etc. with unknowns  $\alpha, \beta$ , etc. which are to be solved for.

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Fix a background vacuum spacetime (M, g). In (B) replace Weyl tensor components  $\alpha[W], \beta[W]$ , etc. with unknowns  $\alpha, \beta$ , etc. which are to be solved for. Get:



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Fix a background vacuum spacetime (M, g). In (B) replace Weyl tensor components  $\alpha[W], \beta[W]$ , etc. with unknowns  $\alpha, \beta$ , etc. which are to be solved for. Get:

Linearized Bianchi equations (LB)	
$ abla_{3} lpha =  abla \hat{\otimes} eta + \Gamma \cdot \Psi$	$\nabla \!\!\!\!/_{4}\beta = d / \!\!\!\!/ v \alpha + \Gamma \cdot \Psi$
$\nabla \!$	$ abla_4( ho,\sigma) = (\mathrm{d}\!\!i \mathrm{v}eta, -\mathrm{c}\!\!i \mathrm{rl}eta) + \Gamma\cdot\Psi$
$ abla_3( ho,\sigma)=(-\mathrm{d}i\!\!\!/\mathrm{v}ar{eta},-\mathrm{c}u\!\!\!/\mathrm{rl}ar{eta})+\Gamma\cdot\Psi$	$\nabla \!$
$ abla_{3}\underline{eta}=-\mathbf{d}\mathbf{i}\mathbf{v}\underline{lpha}+\mathbf{\Gamma}\cdot\mathbf{\Psi}$	$ abla_4 \underline{lpha} = -  abla \hat{\otimes} \underline{eta} + \Gamma \cdot \Psi$

• "Linearized" here refers to the fact that the coefficients  $\Gamma$  in the equations no longer depend on unknowns

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Linearized Bianchi equations (LB)	
$\nabla \!$	$ abla_4eta={\sf d}\!$
$\nabla \!$	$ abla_4( ho,\sigma)=(\mathrm{d}\!\!\!/\mathrm{v}eta,-\mathrm{c}\!\!\!/\mathrm{rl}eta)+\Gamma\cdot\Psi$
$ abla_3( ho,\sigma)=(-\mathrm{d}i\mathrm{v}ar{eta},-\mathrm{c}i\!$	$\nabla \!$
$ abla_3 \underline{eta} = -\mathbf{d} \mathbf{i} \mathbf{v} \underline{lpha} + \mathbf{\Gamma} \cdot \mathbf{\Psi}$	$ abla_4 \underline{lpha} = -  abla \hat{\otimes} \underline{eta} + \Gamma \cdot \Psi$

- "Linearized" here refers to the fact that the coefficients  $\Gamma$  in the equations no longer depend on unknowns
- **Question:** How do we choose which are *constraint equations* and which are *evolution equations*?

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- Starting point: α, <u>α</u> have only one equation each, so to be well-posed these must be viewed as evolution equations

- **Question:** How do we choose which are *constraint equations* and which are *evolution equations*?
- Choose to be "as hyperbolic as possible"
- Starting point: α, <u>α</u> have only one equation each, so to be well-posed these must be viewed as evolution equations
- Unfortunately, there is *no way* to choose evolution equations in such a way that (1) every unknown has a Bianchi-paired evolution equation and (2) the system is not overdetermined

$$\begin{split} \boxed{ \begin{array}{c} & \boxed{ \overrightarrow{\nabla}_{3} \alpha = \overrightarrow{\nabla} \hat{\otimes} \beta + \Gamma \cdot \Psi } \\ & \boxed{ \overrightarrow{\nabla}_{3} \beta = \overrightarrow{\nabla} \rho + {}^{*} \overrightarrow{\nabla} \sigma + \Gamma \cdot \Psi } \\ & \boxed{ \overrightarrow{\nabla}_{3} (\rho, \sigma) = (-d \cancel{i} \lor \underline{\beta}, -c \cancel{i} \varPi r \underline{\beta}) + \Gamma \cdot \Psi } \\ & \boxed{ \begin{array}{c} & \overrightarrow{\nabla}_{3} \underline{\beta} = -d \cancel{i} \lor \underline{\alpha} + \Gamma \cdot \Psi \end{array} \end{split}} \end{split}}$$

#### **Evolution equations**

$$\nabla_{\mathbf{3}} \alpha = \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi$$

$$\nabla_{\mathbf{4}\underline{\alpha}} = -\nabla \hat{\otimes}\beta + \mathbf{\Gamma} \cdot \mathbf{\Psi}$$

#### Constraint equations

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$$\begin{aligned}
\overline{\nabla}_{3}\alpha &= \nabla \widehat{\otimes}\beta + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}\beta &= \nabla \rho + {}^{*}\nabla \sigma + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}(\rho, \sigma) &= (-di \lor \underline{\beta}, -c \psi \lor I \underline{\beta}) + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}\underline{\beta} &= -di \lor \underline{\alpha} + \Gamma \cdot \Psi
\end{aligned}$$

$$\begin{aligned}
\overline{\nabla}_{4\beta} &= di \vee \alpha + \Gamma \cdot \Psi \\
\overline{\nabla}_{4}(\rho, \sigma) &= (di \vee \beta, -c \psi r | \beta) + \Gamma \cdot \Psi \\
\overline{\nabla}_{4\underline{\beta}} &= -\overline{\nabla} \rho + {}^{*} \overline{\nabla} \sigma + \Gamma \cdot \Psi \\
\overline{\nabla}_{4\underline{\alpha}} &= -\overline{\nabla} \hat{\otimes} \underline{\beta} + \Gamma \cdot \Psi
\end{aligned}$$

#### **Evolution equations**

$$\nabla_{\mathbf{4}}\underline{\alpha} = -\nabla \hat{\otimes}\beta + \mathbf{\Gamma} \cdot \mathbf{\Psi}$$

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#### Constraint equations

$$\begin{aligned}
\overline{\nabla}_{3}\alpha &= \overline{\nabla}\widehat{\otimes}\beta + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}\beta &= \overline{\nabla}\rho + {}^{*}\overline{\nabla}\sigma + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}(\rho,\sigma) &= (-d/v\underline{\beta}, -cu/rl\underline{\beta}) + \Gamma \cdot \Psi \\
\overline{\nabla}_{2}\beta &= -d/v\alpha + \Gamma \cdot \Psi
\end{aligned}$$

$$\begin{split} \nabla_{4}(\rho,\sigma) &= (\mathsf{d}_{1}^{\prime} \vee \beta, -\mathsf{c}_{4}^{\prime} \mathsf{r} | \beta) + \mathsf{\Gamma} \cdot \Psi \\ \nabla_{4} \underline{\beta} &= -\nabla \rho + {}^{*} \nabla \sigma + \mathsf{\Gamma} \cdot \Psi \\ \hline \nabla_{4} \underline{\alpha} &= -\nabla \hat{\otimes} \underline{\beta} + \mathsf{\Gamma} \cdot \Psi \end{split}$$

#### **Evolution** equations

$$\nabla_3 \alpha = \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi$$
$$\nabla_4 \beta = \mathbf{d} / \mathbf{v} \alpha + \Gamma \cdot \Psi$$

$$abla_4 \underline{\alpha} = - \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi$$

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#### Constraint equations

$$\nabla \!\!\!\!/_{3}\beta = \nabla \!\!\!\!/ \rho + {}^{*} \nabla \!\!\!/ \sigma + \Gamma \cdot \Psi$$

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$$\begin{aligned}
\overline{\nabla}_{3}\alpha &= \overline{\nabla}\hat{\otimes}\beta + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}\beta &= \overline{\nabla}\rho + {}^{*}\overline{\nabla}\sigma + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}(\rho,\sigma) &= (-d_{i}\nu\underline{\beta}, -c_{i}\nu\underline{\beta}) + \Gamma \cdot \Psi \\
\overline{\nabla}_{3}\beta &= -d_{i}\nu\underline{\alpha} + \Gamma \cdot \Psi
\end{aligned}$$

$$\nabla_4 \beta = \mathbf{d} / \mathbf{v} \alpha + \mathbf{\Gamma} \cdot \mathbf{\Psi}$$

$$abla_4(
ho,\sigma) = (d\!\!i \! \mathrm{v}eta, - \! \mathrm{c} \! \psi \! \mathrm{rl}eta) + \mathsf{\Gamma} \cdot \Psi$$

$$\nabla _{4}\underline{\beta} = -\nabla \rho + {}^{*}\nabla \sigma + \Gamma \cdot \Psi$$

$$\nabla_{4\underline{\alpha}} = -\nabla \hat{\otimes} \underline{\beta} + \Gamma \cdot \Psi$$

### **Evolution equations**

$$\begin{split} & \nabla_{\mathbf{3}} \alpha = \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi & \nabla_{\mathbf{4}} \underline{\alpha} = -\nabla \hat{\otimes} \underline{\beta} + \Gamma \cdot \Psi \\ & \nabla_{\mathbf{4}} \beta = \mathsf{d} /\!\! \mathsf{v} \alpha + \Gamma \cdot \Psi & \nabla_{\mathbf{3}} (\rho, \sigma) = (-\mathsf{d} /\!\! \mathsf{v} \underline{\beta}, -\mathsf{c} \not\! \mathsf{v} \mathsf{r} \mathsf{l} \underline{\beta}) + \Gamma \cdot \Psi \end{split}$$

Constraint equations

$$\nabla_3 \beta = \nabla \rho + {}^* \nabla \sigma + \Gamma \cdot \Psi$$

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### **Evolution equations**

### Constraint equations

$$\forall_{3}\beta = \forall \rho + {}^{*}\forall \sigma + \Gamma \cdot \Psi \qquad \forall_{4}(\rho, \sigma) = (\mathsf{d}' \mathsf{v}\beta, -\mathsf{c} \psi \mathsf{r} \mathsf{l}\beta) + \Gamma \cdot \Psi$$

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$$\begin{array}{c} \overline{\forall}_{3}\alpha = \overline{\forall}\hat{\otimes}\beta + \Gamma \cdot \Psi \\ \hline \overline{\forall}_{3}\beta = \overline{\forall}\rho + {}^{*}\overline{\forall}\sigma + \Gamma \cdot \Psi \\ \hline \overline{\forall}_{3}\beta = \overline{\forall}\rho + {}^{*}\overline{\forall}\sigma + \Gamma \cdot \Psi \\ \hline \overline{\forall}_{3}(\rho,\sigma) = (-d_{1}^{i}v\underline{\beta}, -cu^{i}r\underline{\beta}) + \Gamma \cdot \Psi \\ \hline \overline{\forall}_{3}\underline{\beta} = -d_{1}^{i}v\underline{\alpha} + \Gamma \cdot \Psi \\ \hline \overline{\forall}_{4}\underline{\beta} = -\overline{\forall}\rho + {}^{*}\overline{\forall}\sigma + \Gamma \cdot \Psi \\ \hline \overline{\forall}_{4}\underline{\alpha} = -\overline{\forall}\hat{\otimes}\underline{\beta} + \Gamma \cdot \Psi \\ \hline \end{array}$$

#### **Evolution equations**

$$\begin{split} & \nabla_{3} \alpha = \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi \\ & \nabla_{4} \beta = \mathsf{d} / \mathsf{v} \alpha + \Gamma \cdot \Psi \\ & \nabla_{4} \underline{\beta} = - \nabla \rho + {}^{*} \nabla \sigma + \Gamma \cdot \Psi \end{split}$$

#### Constraint equations

$$\begin{split} \overline{\nabla}_{3}\alpha &= \overline{\nabla}\hat{\otimes}\beta + \Gamma \cdot \Psi \\ \overline{\nabla}_{3}\beta &= \overline{\nabla}\rho + {}^{*}\overline{\nabla}\sigma + \Gamma \cdot \Psi \\ \overline{\nabla}_{3}(\rho,\sigma) &= (-d_{1}^{j}v\underline{\beta}, -c_{4}^{j}rl\underline{\beta}) + \Gamma \cdot \Psi \\ \overline{\nabla}_{3}(\rho,\sigma) &= (-d_{1}^{j}v\underline{\beta}, -c_{4}^{j}rl\underline{\beta}) + \Gamma \cdot \Psi \\ \overline{\nabla}_{3}\underline{\beta} &= -d_{1}^{j}v\underline{\alpha} + \Gamma \cdot \Psi \\ \end{split}$$

#### **Evolution equations**

$$\begin{split} & \nabla_{3} \alpha = \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi \\ & \nabla_{4} \beta = \mathsf{d} i \mathsf{v} \alpha + \Gamma \cdot \Psi \\ & \nabla_{4} \underline{\beta} = - \nabla \rho + {}^{*} \nabla \sigma + \Gamma \cdot \Psi \end{split}$$

#### Constraint equations

$$abla_4(
ho,\sigma) = (\mathbf{d}/\mathbf{v}eta, -\mathbf{c}/\mathbf{r}|eta) + \mathbf{\Gamma}\cdot \mathbf{\Psi}$$

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#### **Evolution equations**

$$\begin{cases} \nabla_{3}\alpha &= \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi \\ \nabla_{4}\beta &= \mathsf{d} i \mathsf{v} \alpha + \Gamma \cdot \Psi \\ \nabla_{3}(\rho, \sigma) &= (-\mathsf{d} i \mathsf{v} \underline{\beta}, -\mathsf{c} \mathsf{v} \mathsf{t} \mathsf{r} | \underline{\beta}) + \Gamma \cdot \Psi \\ \nabla_{4}\underline{\beta} &= -\nabla \rho + {}^{*} \nabla \sigma + \Gamma \cdot \Psi \\ \nabla_{4}\underline{\alpha} &= -\nabla \hat{\otimes} \underline{\beta} + \Gamma \cdot \Psi \end{cases}$$

### Constraint equations

$$\begin{cases} \Xi := \nabla_3 \beta - \nabla \rho - {}^* \nabla \sigma - \Gamma \cdot \Psi &= 0\\ (P, Q) := \nabla_4(\rho, \sigma) - (di \nu \beta, -c \mu r \beta) - \Gamma \cdot \Psi &= 0\\ \Xi := \nabla_3 \underline{\beta} + di \nu \underline{\alpha} - \Gamma \cdot \Psi &= 0 \end{cases}$$

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#### **Evolution equations**

$$\begin{cases} \nabla_{3}\alpha &= \nabla \hat{\otimes} \beta + \Gamma \cdot \Psi \\ \nabla_{4}\beta &= \mathsf{d} i \mathsf{v} \alpha + \Gamma \cdot \Psi \\ \nabla_{3}(\rho, \sigma) &= (-\mathsf{d} i \mathsf{v} \underline{\beta}, -\mathsf{c} \mathsf{v} \mathsf{t} \mathsf{r} | \underline{\beta}) + \Gamma \cdot \Psi \\ \nabla_{4}\underline{\beta} &= -\nabla \rho + {}^{*} \nabla \sigma + \Gamma \cdot \Psi \\ \nabla_{4}\underline{\alpha} &= -\nabla \hat{\otimes} \underline{\beta} + \Gamma \cdot \Psi \end{cases}$$

#### Constraint equations

$$\begin{cases} \Xi := \nabla_3 \beta - \nabla \rho - {}^* \nabla \sigma - \Gamma \cdot \Psi &= 0\\ (P, Q) := \nabla_4(\rho, \sigma) - (di \nu \beta, -c \psi r | \beta) - \Gamma \cdot \Psi &= 0\\ \Xi := \nabla_3 \underline{\beta} + di \nu \underline{\alpha} - \Gamma \cdot \Psi &= 0 \end{cases}$$

**Remark:** A collection of tensor fields  $\Psi := (\alpha, \beta, \rho, \sigma, \underline{\beta}, \underline{\alpha})$  satisfies (LB) if and only if it satisfies both the evolution and constraint equations.

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# Propagation of constraints

• **Question:** Are the constraints  $\Xi = \Xi = P = Q = 0$  preserved by the evolution?

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# Propagation of constraints

- **Question:** Are the constraints  $\Xi = \Xi = P = Q = 0$  preserved by the evolution?
- Answer: No! Not unless additional constraints are satisfied by the unknowns.

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# Propagation of constraints

- **Question:** Are the constraints  $\Xi = \Xi = P = Q = 0$  preserved by the evolution?
- Answer: No! Not unless additional constraints are satisfied by the unknowns.
- Note: the unknowns  $\Psi = (\alpha, \beta, \rho, \sigma, \underline{\beta}, \underline{\alpha})$  belong, at every point  $p \in M$ , to the vector space

$$\mathcal{V}_{\rho} = \left\{ \begin{smallmatrix} \mathsf{symmetric traceless} \\ 2\text{-covariant tensors} \end{smallmatrix} \right\} \times \mathcal{T}_{\rho}^* \mathcal{S}_{u,\underline{u}} \times \mathbb{R} \times \mathbb{R} \times \mathcal{T}_{\rho}^* \mathcal{S}_{u,\underline{u}} \times \left\{ \begin{smallmatrix} \mathsf{symmetric traceless} \\ 2\text{-covariant tensors} \end{smallmatrix} \right\}$$

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# Algebraic constraints

• Note: the unknowns  $\Psi = (\alpha, \beta, \rho, \sigma, \underline{\beta}, \underline{\alpha})$  belong, at every point  $p \in M$ , to the vector space

$$\mathcal{V}_{p} = \left\{ \begin{smallmatrix} \mathsf{symmetric traceless} \\ 2\text{-covariant tensors} \end{smallmatrix} \right\} \times \mathcal{T}_{p}^{*} \mathcal{S}_{u,\underline{u}} \times \mathbb{R} \times \mathbb{R} \times \mathcal{T}_{p}^{*} \mathcal{S}_{u,\underline{u}} \times \left\{ \begin{smallmatrix} \mathsf{symmetric traceless} \\ 2\text{-covariant tensors} \end{smallmatrix} \right\}$$

### Theorem (S.)

Fix a background spacetime (M, g) admitting a double null foliation. There is a pointwise linear map  $\mathfrak{L}_W|_p : \mathcal{V}_p \to T_p^* S_{u,\underline{u}} \times T_p^* S_{u,\underline{u}} \times \mathbb{R} \times \mathbb{R}$ , depending only on the Weyl tensor of (M, g) such that any solution of (LB) satisfies

$$\mathfrak{L}_W \Psi = 0. \tag{1}$$

Moreover, if (M,g) is not Minkowski spacetime, then

 $\dim \ker \mathfrak{L}_W < \dim \mathcal{V}.$ 

That is, solutions to (LB) must lie in a codimension  $\geq 1$  subspace of  $\mathcal{V}$ .

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That is, solutions to (LB) must lie in a codimension  $\geq 1$  subspace of  $\mathcal{V}$ .

If  $\alpha[W]$  or  $\underline{\alpha}[W]$  is nonzero, then we can write a basis for the  $\alpha, \underline{\alpha}$  part of ker  $\mathfrak{L}_W$ :

$$\left\{ (\alpha, \underline{\alpha}) = (\alpha[W], \underline{\alpha}[W]), \quad (\alpha, \underline{\alpha}) = ({}^*\alpha[W], -{}^*\underline{\alpha}[W]) \right\}$$
(3)

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Very constrained!

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• Take derivatives of the constraint quantities  $\Xi, \underline{\Xi}, P$ , and Q

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- Take derivatives of the constraint quantities  $\Xi, \underline{\Xi}, P$ , and Q
- Insert expressions from the evolution equations and the null structure equations for  $\Gamma$  of the background spacetime
- Obtain many terms

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Figure: Lowest-order expansion of  $\nabla_4 \equiv$ 

Christopher Stith	(University of Michigan)	
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October 2024

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 After grouping terms, obtain for every differential constraint Ξ, Ξ, P, Q a differential equation of the form

 $abla_4[\mathsf{diff. constraint}] = \left\{ \begin{smallmatrix} \mathsf{terms which are 0}\\ \mathsf{iff diff. constraints vanish} \end{smallmatrix} 
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• Therefore 
$$\mathfrak{L}_W \Psi = 0$$

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Algebraic constraints - consequences and further questions

Consequences

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# Algebraic constraints - consequences and further questions

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• Solutions to (LB) are more constrained than expected

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# Thank You!

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